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# TECHNICAL MEMORANDUM

(TM Series)

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Utility Program Description

Milestone XI

Subroutine Timer (SRTIMER)

By

H. W. Houghton

28 March 1963

Approved By

J. D. Marioni

SYSTEM

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#### SUBROUTINE IDENTIFICATION

- A. Title: Subroutine Timer (SRTIMER) - Ident K29, Mod. 01  
B. Programmed: 20 March 1963, H. W. Houghton, System Development Corporation  
C. Documented: 27 March 1963, H. W. Houghton, System Development Corporation

#### PURPOSE

SRTIMER is generalized routine for timing COP system programs.

#### USAGE

- A. Calling Sequence:

L	NOP	R
	SLJ	4 SRTIMER
L + 1	Normal Return	
	ZRO	N
L + 2	A	
L + 3	B	
L + 4	C	
L + 5	P <sub>1</sub>	
L + 6	P <sub>2</sub>	
.	.	
.	.	
.	.	
L + 2 + N	P <sub>N-3</sub>	
L + 3 + N	M <sub>1</sub>	
.	.	•
.	.	
.	.	
L + 2 + N + R	M <sub>R</sub>	

Where R = number of modifications

N = number of parameters (including the three control parameters A, B, and C for SRTIMER)

A = number of times the program is to be timed.

= 0 for timing the program the necessary number of times for it to run 10 to 100 seconds to obtain an accurate average.

B = 0 for setting the Accumulator, Q-Register, and Index Registers as entrance parameters.

= 1 for normal function calling sequence, i.e., normal return in  $\alpha + 1$  with parameters following.

= 2 for two returns (normal and error) in  $\alpha + 1$  and  $\alpha + 2$ .

= 3 for return following calling sequence.

C = name in BCD of program to be timed.

$P_1$  = Accumulator contents (B = 0) or first parameter of calling sequence (B  $\neq$  0).

$P_2$  = Q-Register contents (B = 0) or second parameter (B  $\neq$  0).

$P_3$  = Index designation (B = 0) or third parameter (B  $\neq$  0).

$P_4$  = Index contents (B = 0) or fourth parameter (B  $\neq$  0).

If B = 0,  $P_5$  and  $P_6$ ,  $P_7$  and  $P_8$  may be given for a second and third index register.

$P_N$  = Nth parameter (B  $\neq$  0).

$M_1$  = first modification (B  $\neq$  0).

$M_R$  = Rth modification (B  $\neq$  0).

#### B. Format of Function Card

\*SRTIMER A B C  $P_1 \dots P_N, M_1 \dots M_R$

where A, B, C,  $P_1 \dots P_N, M_1, \dots M_R$  are as given above.

#### C. Printouts:

SRTIMER will printout on-line the running time of the program being timed. The printout is as follows:

TIME FOR CCCCCCCC ROUTINE IS XXXXX SEC, YYYYYY MICROSEC.

Also, if desired, SRTIMER will printout:

COMPUTER IS ZZ.ZZ PERCENT FAST (or SLOW)

This is the speed of the computer compared with the machine specifications.

- D. There are no error returns from SRTIMER.
- E. Tape assignments depend on the program being timed.
- F. Jump key 2 is set if the computer speed printout is desired.

#### METHOD

On the first entry to SRTIMER the speed of the computer is checked by doing a loop of known length. The constants used in the timing portion are adjusted to compensate for the difference of the individual computer from the 1604 specifications. Also a check is made to determine whether SRTIMER was loaded in an even or an odd location. The set of constants used is dependent on the bank in which the program starts.

For all entries to SRTIMER the type of calling sequence needed by the routine to be timed is determined and an appropriate calling sequence is set up. COP is referenced to find the starting location of the routine and this address is placed in the return jump. The Real Time Clock is set to - 2 and started. When the clock turns to zero, the return jump to the subroutine is made. After the subroutine is run, control is returned to SRTIMER. If A, i.e. the "number of times" parameter equals 0 or 1, the computer will immediately start executing a loop of known duration until the clock changes. When the time in the loop is subtracted from the total times, we have the time in the subroutine. If A is other than 0 or 1, the return jump to the subroutine is executed the proper number of times before the loop is started. After the routine has been timed, the total time is divided by the number of times the routine has been executed. This gives us the time for one execution of the routine. In the case that A = 0, SRTIMER checks to see if the routine took longer than ten seconds. If not, it will determine a number of times (10, 100, 1,000 or 10,000) such that at least ten seconds will elapse during the timing and executes the routine this number of times.

#### RESTRICTIONS

- A. The accuracy is dependent on the number of times the subroutine is executed. If the subroutine is operated one time the results will be accurate within .05% or twenty microseconds, whichever is greater. The error can be reduced to .05% or 2 microseconds by executing the subroutine more times. Any routines that use I-O devices will probably produce inconsistent times due to variance in speed of the devices.
- B. "A" must be equal to 1 if the routine does not housekeep itself.
- C. "A" should not be equal to 0 if the routine initiates an I-O operation and does not wait for its completion.
- D. Routine being timed must not use the Real Time Clock.
- E. The on-line printer is used. Other components may be needed for the subroutine being timed.
- F. SRTIMER uses subroutines OUTPUT, SUBERR, and FLOAT.
- G. Index Registers 1, 2 and 3 are always used. The others may be used by the subroutines being timed. All of the index registers are saved and restored prior to exiting.
- H. COPII must be used. SRTIMER refers to ADDROF.
- I. If a series of programs are being timed and there is danger of COPII reallocating space above 10000B, a function card of the following format should be used.

\* 10000B SRTIMER . . . .

This will reload SRTIMER at 10000B and remove the possibility of being destroyed by the reallocation of space.

#### TIMING

The timing is dependent on the subroutine being timed and whether or not it is in core when SRTIMER is called.

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#### STORAGE REQUIREMENTS

##### Space Allocation:

Program	146
Constants	26
Printouts	12
Temporary Storage	<u>111</u>
TOTAL	295

#### VALIDATION TESTS

A break point was set to stop the computer just before the clock was started. When the computer halted the break point was reset to stop the computer after a fairly long routine (approximately 1/3 minute) had been executed. The observed time between restart and the second break point and the computed time was equal. Also, two octals were added to the deck to allow a jump to the normal return without executing any subroutine. This deck was operated over 100 times with A equal to various values. For  $A = 1$ , the results were between -20 and 20 microseconds. As A was increased the error bounds decreased until they reached  $\pm 2$   $\mu$ seconds. Without the octals several subroutines were operated. When runs of a given program were repeated, the results were within .05% of the average value.

#### REFERENCES

- A. TM-966621/005/00 Execution Times for Instructions on the CDC 1604 Computer, 2 November 1962.
- B. LMSD-447578, System Manual Subroutine Description of OUTPUT, 3 June 1960, pages 45.14.01 f.f.
- C. LMSD-44578, System Manual Subroutine Description of SUBERR, 21 July 1961, pages 50.06.01 f.f.
- D. TM-(L)-705/014/00 SCF System Manual Subroutine Description of FLOAT, 11 September 1962.

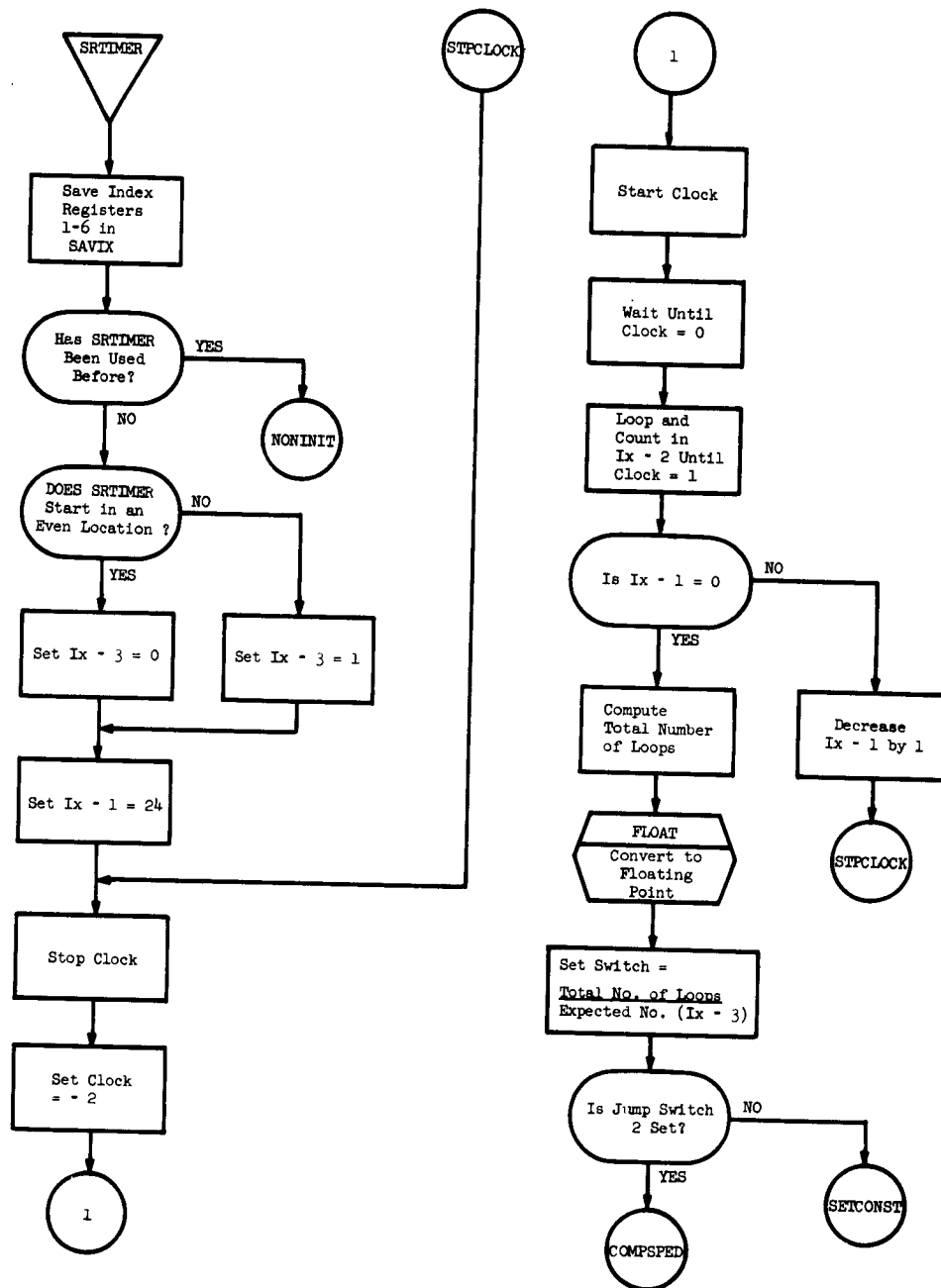


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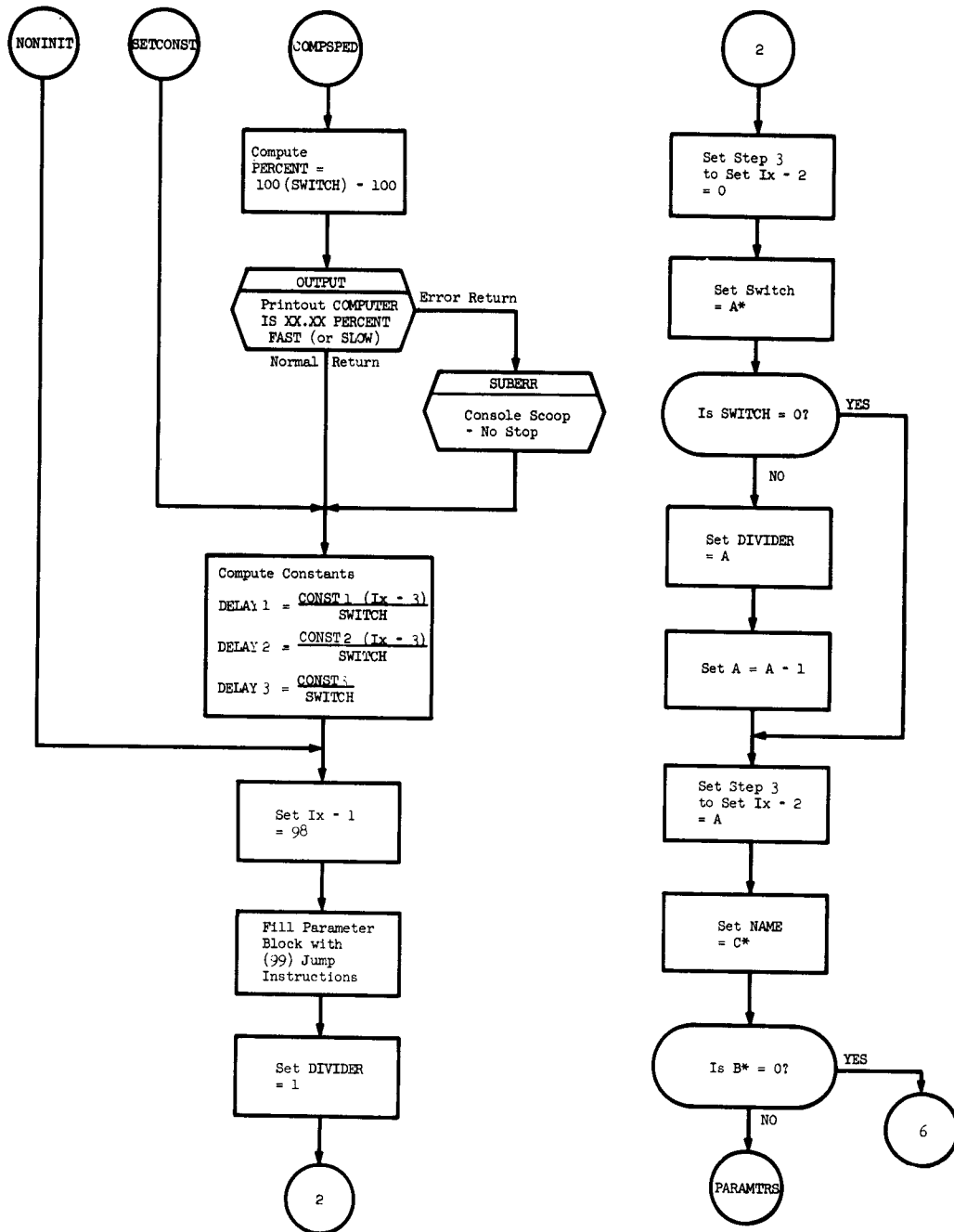
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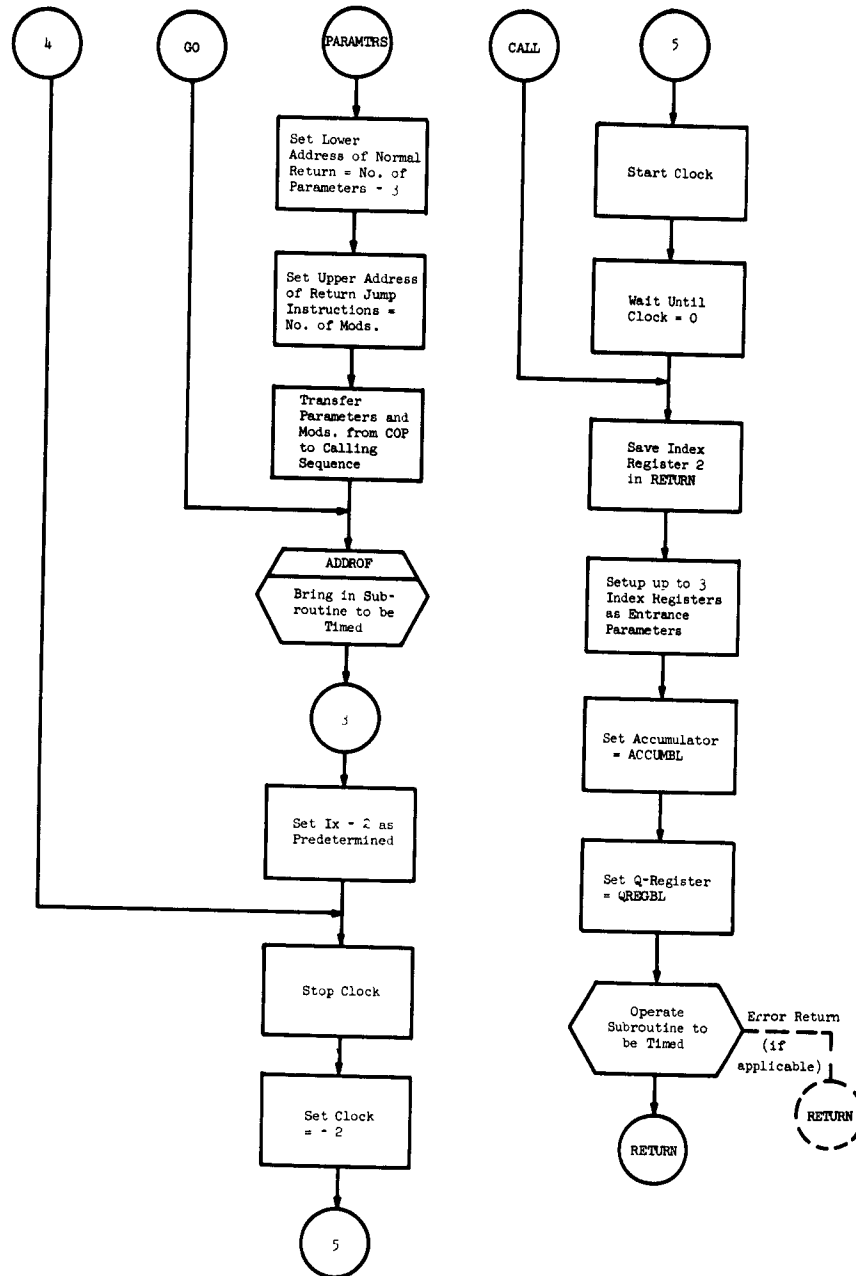


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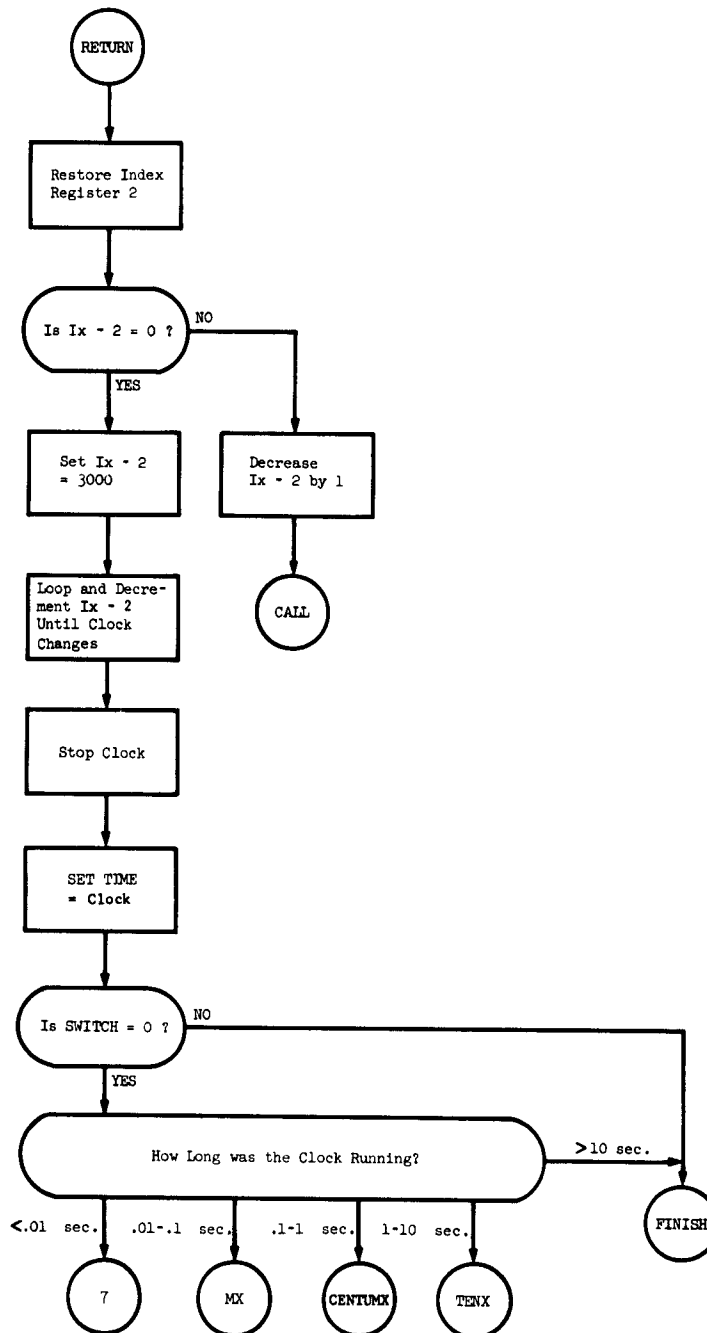


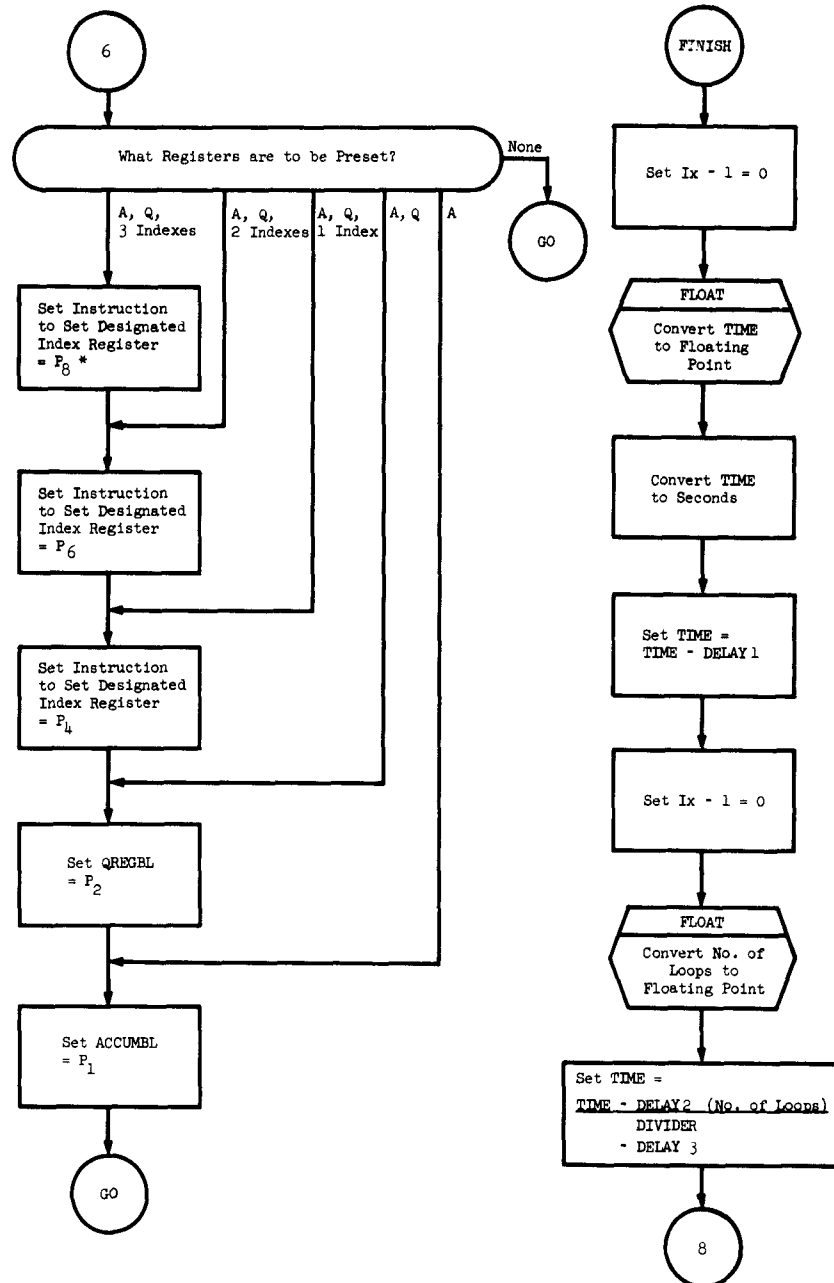


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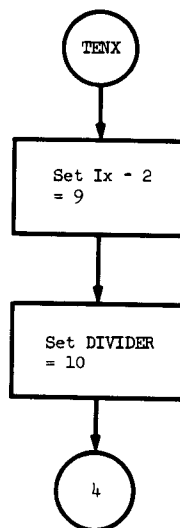
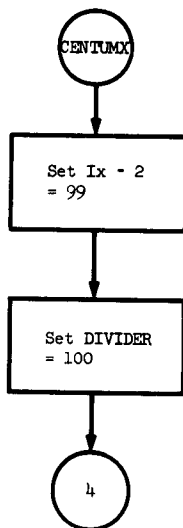
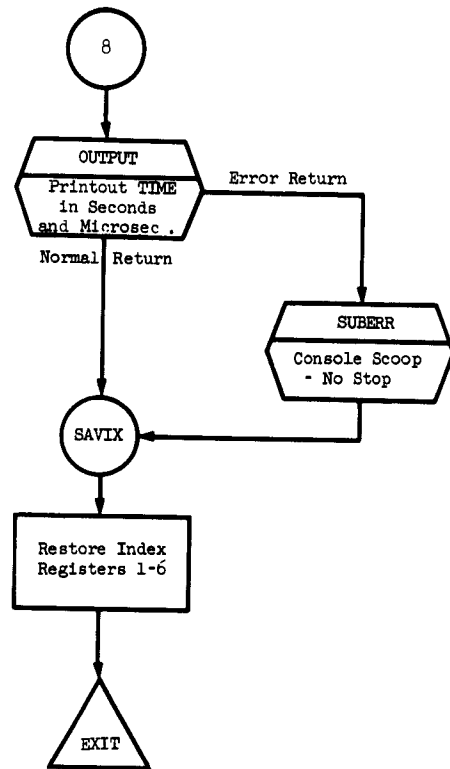
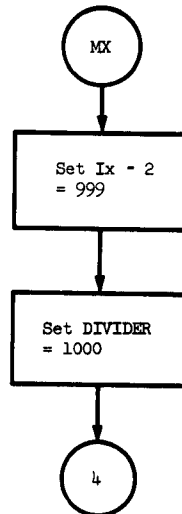
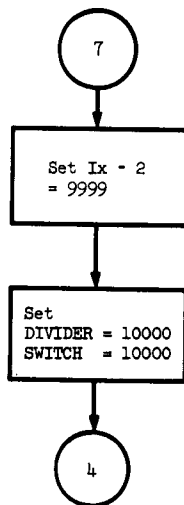




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ALPERIN, N. I.	22153	KEYES, R. A.	24073
ARMSTRONG, E.	24123	KINKEAD, R. L.	22093
BERNARDS, R. M.	SUNNYVALE	KNEEMEYER, J. A.	22088A
BIGGAR, D.	24118A	KNIGHT, R. D.	22119
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FRIEDEN, H. J.	22082	RUSSELL, R. S.	14054
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HENLEY, D. E.	22094B	SKELTON, R. H.	22148
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WINTER, J. E.  
WISE, R. C.  
WONG, J. P.  
ZACHTE, S. A.  
ZUBRIS, C. J.

22156  
24117  
22085  
SUNNYVALE  
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24075

VORHAUS, A. H.  
WAGNER, I. T.  
WARSHAWSKY, S. B.  
WEST, G. D.  
WEST, G. P.  
WILSON, G. D.

24076A  
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SUNNYVALE  
22116A  
24124



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Santa Monica, California  
UTILITY PROGRAM DESCRIPTION -  
MILESTONE XI SUBROUTINE TIMER(SRTIMER).  
Scientific rept., TM(L)-715/037/00,  
by H. W. Houghton. 28 March 1963,  
11p., 4 refs.  
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Unclassified report

DESCRIPTORS: Satellite Networks.  
Programming (Computers).

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Reports that SRTIMER (Subroutine Timer)  
is a generalized routine for timing  
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